## Code: 17MEMD2T1

I M.Tech - II Semester - Regular/Supplementary Examinations OCTOBER - 2020

## MECHANISM DESIGN AND SYNTHESIS (MACHINE DESIGN)

## Duration: 3 hours

Max Marks: 60
Answer the following questions

1. a) Calculate the degrees of the freedom for the following.

$$
10 \mathrm{M}
$$


(a)

(b)

(c)

(e)
b) What is Kutzback's criterion for degree of freedom of plane mechanisms? In what way Gruebler's Criterion is different from it?

5 M
(OR)
2. a) Describe various inversions of single and double slider crank chain mechanisms giving suitable examples. 10 M
b) In four bar mechanism, $L_{1}$ and $L_{3}$ represent the lengths of fixed link and the coupler. $L_{2}$ and $L_{4}$ represent the lengths of the other two links (cranks). The table below gives five sets of link dimensions (in mm ). What is the resulting mechanism for each set?

| Set | $\mathrm{L}_{1}$ | $\mathrm{~L}_{2}$ | $\mathrm{~L}_{3}$ | $\mathrm{~L}_{4}$ |
| :--- | :--- | :--- | :--- | :--- |
| A | 500 | 20 | 150 | 300 |
| B | 500 | 180 | 20 | 200 |
| C | 20 | 300 | 400 | 200 |
| D | 200 | 20 | 150 | 70 |
| E | 60 | 200 | 180 | 80 |

3. Design a four bar linkage to move link $C D$ from $C_{1} D_{1}$ to $\mathrm{C}_{2} \mathrm{D}_{2}$ by graphical linkage synthesis.

(OR)
4. The linkage shown in figure, calculate and plot the angular displacement of links 3 and 4 and the path coordinates of point P with respect to the angle of the input crank $\mathrm{O}_{2} \mathrm{~A}$ for one revolution.

5. Design a four bar linkage which will move a line on its coupler link such that a point $P$ on that line will be first at $P_{1}$ and later at $\mathrm{P}_{2}$ and will also rotate the line through an angle $\delta_{2}$ between those two precision positions.

(OR)
6. Design a four bar linkage to move the link CD from the position $\mathrm{C}_{1} \mathrm{D}_{1}$ to $\mathrm{C}_{2} \mathrm{D}_{2}$ and then to position $\mathrm{C}_{3} \mathrm{D}_{3}$. Use different moving pivots than CD. Find the fixed pivot locations.


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7. a) PQRS is a four bar chain with link PS fixed. The lengths of links are $\mathrm{PQ}=62.5 \mathrm{~mm}, \mathrm{QR}=175 \mathrm{~mm}, \mathrm{RS}=112.5 \mathrm{~mm}$ and PS $=200 \mathrm{~mm}$. The crank PQ rotates at $10 \mathrm{rad} / \mathrm{sec}$ clockwise. Draw velocity and acceleration diagram, when angle $\mathrm{QPS}=60^{\circ}$ and Q and R lie on the same side of PS. Find the angular velocity and angular acceleration of links $Q R$ and RS. Choose a suitable scale for configuration of velocity and acceleration diagrams.
b) Give the classification of various cam-follower systems.

5 M

## (OR)

8. In the steam engine mechanism shown in below figure, the crank $A B$ rotates at 200rpm clockwise. Find the velocities of C, D, E, F and G and acceleration of slider at C. Here lengths of $\mathrm{AB}=12 \mathrm{~cm}, \mathrm{BC}=48 \mathrm{~cm}, \mathrm{CD}=18 \mathrm{~cm}, \mathrm{DE}=36 \mathrm{~cm}$, $\mathrm{EF}=12 \mathrm{~cm}$ and $\mathrm{FG}=36 \mathrm{~cm}$.

